

Q. Consider the following concurrently running processes P0 and P1.

Shared data:

```
bool waiting [0] = false, waiting [1] = false;  
int turn = 0;
```

Process P0:

```
while (true)  
{  
a1  waiting [0] = true;  
a2  while (turn != 0)  
    {  
a3      while (waiting [1]);  
a4      turn = 0;  
    }  
}
```

Critical Section code

waiting [0] = false;

Remainder Section code

Process P1:

```
while (true)  
{  
b1  waiting [1] = true;  
b2  while (turn != 1)  
    {  
b3      while (waiting [0]);  
b4      turn = 1;  
    }  
}
```

Critical Section code

waiting [1] = false;

Remainder Section code

Give a sequence of instructions in terms of **ai**'s and **bi**'s to show that mutual exclusion is not satisfied.

Sequence:

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Q.3. (15 points) There are 3 robots (red, blue, green) – each is controlled by its own process. We need to ensure that the robots only move in the following order: red, blue, green, red, blue, green, etc. Add the necessary code below that performs the appropriate initializations and enforces this execution order. Use only semaphores for your synchronization.

Shared Variables:

SemaphoreR=1....., ..B=0....., G=0.....;

Process Robot_red
do {

MOVE();

}while(true);

Process Robot_blue
do {

MOVE();

}while(true);

Process Robot_green
do {

MOVE();

}while(true);